



## **ROBOTIC CELL** Innovations and specificities

## VISION SYSTEM

- . . . . . . . . . . . . . . . . Castings can be loaded without a specific support.
- Castings can be inspected (dimensions, quality, etc.).
  - A castings positioning check can be carried out for simultaneous multiple production processes.

#### **COMPLIANCE GRINDING**

- Dimensional differences, defects located on jointing faces and moulding variations are some of the issues requiring adaptation of robot trajectories.
- Compliance systems developed by SiiF for spindles or castings clamps provide a finishing process suited to each casting.

## **CASTINGS MARKING**

- The development of quality systems and the need for individual tracking of castings requires increasingly the use of clearly identified markings (letters and numbers) or a DataMatrix code.
- SiiF offers all marking systems in accordance with customer specifications.

## AUTOMATIC GRIPPER CHANGE

- The gripper automatic coupler is used to quickly change to adapt to production.
- This gripper coupler optimises cell use.

#### **CHANGE OF TOOLS**

Automatic tool change quickly and safely changes one tool for another and optimises cell operating time.

#### TOOLS OR CASTINGS HANDLING

- For large, heavy castings the robot holds the finishing tools.
- Castings can be fitted onto rotating supports, for optimum exposure of the areas to be finished by the robot.
- Small and medium-sized castings whose weight is compatible with robot capacities are held using a suitable clamp and are processed to the various finishing tools by robot.



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Cast rion RC

Aluminum RC

Offline programming