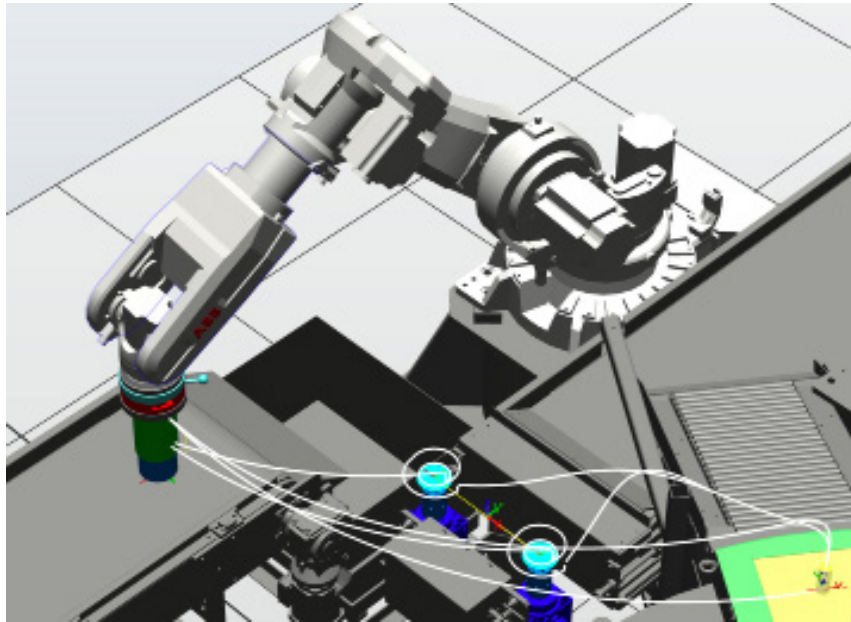




OFFLINE PROGRAMMING



ALL THE SIIF ROBOTIC CELLS CAN BE PROGRAMED OFFLINE

These programming methods are the best way to reduce significantly the production stop when creating a new reference.

- Offline robot trajectory programming (RobotStudio, KUKA.Sim...)
- Offline programming of 3D vision from the CAD piece.

